OMRON

Fleet Operations Workspace iQ

User's Manual

- NOTE -

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form, or by any means, mechanical, electronic, photocopying, recording, or otherwise, without the prior written permission of OMRON.

No patent liability is assumed with respect to the use of the information contained herein. Moreover, because OMRON is constantly striving to improve its high-quality products, the information contained in this manual is subject to change without notice. Every precaution has been taken in the preparation of this manual. Nevertheless, OMRON assumes no responsibility for errors or omissions. Neither is any liability assumed for damages resulting from the use of the information contained in this publication.

Trademarks –

- Sysmac and SYSMAC are trademarks or registered trademarks of OMRON Corporation in Japan and other countries for OMRON factory automation products.
- Windows and Windows 10 are registered trademarks of Microsoft Corporation in the USA and other countries. The official name of Windows 10 is Microsoft Windows 10 Operating System.
- CFAST is a registered trademark of CompactFlash Association.
- ODVA and EtherNet/IPTM are trademarks of ODVA Inc.
- Other company names and product names in this document are the trademarks or registered trademarks of their respective companies.
- Chrome is a trademark of Google LLC.

Copyrights -

Microsoft product screen shots used with permission from Microsoft Corporation. This product incorporates certain third party software.

Introduction

Thank you for purchasing or choosing to evaluate Fleet Operations Workspace iQ (FLOW iQ). This manual is OMRON's original instructions describing the setup, operation, and use of FLOW iQ. This manual contains information that is necessary for safe and proper use of FLOW iQ. Please read this manual and make sure you understand the functionality and performance of FLOW iQ before attempting to use it in a controlled system.

Keep this manual in a safe place where it will be available for reference during operation.

Overview

FLOW iQ is an analytical tool that tracks, stores and displays a fleet's operational status and performance using a graphical format. It provides current and historical data to plan and take preemptive actions for fleet optimization purposes.

The FLOW iQ application and associated database are included in the Fleet Operations Workspace Core package. This application runs on the Fleet Manager.

Requirements

FLOW iQ with Wireless Diagnostics requires the installation and proper operation of the following OM-RON products:

- Fleet Manager
- · Fleet Operations Workspace Core version 4.0 or higher
- SetNetGo 7.1.1 or higher
- MobilePlanner 8.0 or higher

Intended Audience

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent):

- Personnel in charge of planning Factory Automation systems.
- · Personnel in charge of evaluating Factory Automation systems.
- Personnel in charge of introducing Factory Automation systems.
- Personnel in charge of designing Factory Automation systems.
- · Personnel in charge of installing and maintaining Factory Automation systems.
- · Personnel in charge of managing Factory Automation systems and facilities.

Applicable Products

This manual contains information for the proper use of FLOW iQ. FLOW iQ operates on the Fleet Manager with SetNetGo and MobilePlanner.

Notation

The following notation types are used in this document.

• [IP] is substituted for application-specific IP addresses.

• The terms AMR and robot are used interchangeably.

Sections in this Manual



CONTENTS

Introduction	
Overview	
Requirements	
Intended Audience	1
Applicable Products	1
Notation	1
Sections in this Manual	
Manual Information	6
Page Structure	6
Special Information	7
Terms and Conditions Agreement	
Warranty and Limitations of Liability	
Application Considerations	
Disclaimers	9
Safety Precautions	
Definition of Precautionary Information	
Symbols	
Warning	
Cautions	
Precautions for Safe Use	
Precautions for Correct Use	
Regulations and Standards	
Software Licenses and Copyrights	
Related Manuals	
Related Product Manuals	16
Glossary	
Revision History	12

Section 1 User Interface

1-1	Inter	face Structure	
1-2	Side	Bar	
1-3	Info	mation Area	
1-4	Title	Bar	
	1-4-1	Date/Time	
	1-4-2	Language	
	1-4-3	User	
	1-4-4	License	
1-5	Men		
	1-5-1	Home	
	1-5-2	Robot Status	
	1-5-3	Job History	

1-5-4 Battery Info	1-10
1-5-5 Map	
1-5-6 Wireless Diagnostics	
1-5-7 API and Download	

Section 2 Installation

2-1	Installation Steps	2-2
2-2	Version Conflicts	2-4
	Restore Default Settings	
	Restore Derudit Octilings	
	-	
2-4	Licensing	2-7

Section 3 Operation

3-1 Acc	cessing FLOW iQ	
3-2 Con	nmon Operations	
3-2-1	Date/Time Settings	
3-2-2	Map View Controls	
3-3 Hon	ne Functions	
3-4 Rob	oot Status	
3-4-1	Fleet Status	
3-4-2	Individual Robot Status	
3-5 Job	History	
3-5-1	Job History Graph	
3-5-2	Job History Segments & Jobs	
3-6 Batt	tery Info	
3-6-1	Battery Info Graphs	
3-7 Map	0	
3-7-1	Position Density Map	
3-7-2	Localization Map	
3-7-3	Wireless Quality Map	
3-7-4	Floor Map	3-16
3-8 Wire	eless Diagnostics	3-17
3-8-1	Signal	
3-8-2	Ping	
3-8-3	BSSID	
3-8-4	Other	
3-8-5	Roams	
	Roams	
3-9 API	and Download	3-22

Manual Information

This section provides information about the contents and structure of this manual.

Page Structure

The following page structure is used in this manual.



Note: This illustration is provided as a sample. It will not literally appear in this manual.

Item	Explanation	Item	Explanation
А	Level 1 heading	Е	Special Information
В	Level 2 heading	F	Manual name
С	Level 3 heading	G	Page tab with the number of the main section
D	Step in a procedure	Н	Page number

Special Information

Special information in this manual is classified as follows:



Precautions for Safe Use

Precautions on what to do and what not to do to ensure safe usage of the product.



Precautions for Correct Use

Precautions on what to do and what not to do to ensure proper operation and performance.



Additional Information

Additional information to read as required. This information is provided to increase understanding or make operation easier.



Version Information

Information on differences in specifications and functionality between different versions.

Terms and Conditions Agreement

Warranty and Limitations of Liability

Warranty

Exclusive Warranty

Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, expressed or implied.

Limitations

OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or otherwise of any intellectual property right.

Buyer Remedy

Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding the Products unless Omron's analysis confirms that the Products were properly handled, stored, installed and maintained and not subject to contamination, abuse, misuse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty.

See http://www.omron.com/global/ or contact your Omron representative for published information.

Limitations of Liability

OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CON-SEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY. Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.

Application Considerations

Suitability for Use

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND IN-STALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

Programmable Products

- Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.
- Omron Companies shall not be responsible for the operation of the user accessible operating system (e.g. Windows, Linux), or any consequence thereof.

Disclaimers

Performance Data

Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.

Change in Specifications

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

Errors and Omissions

Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

Safety Precautions

Definition of Precautionary Information

The following notation is used in this manual to provide precautions required to ensure safe usage of FLOW iQ. The safety precautions that are provided are extremely important to safety. Always read and heed the information provided in all safety precautions. The following notations are used.

Indicates a potentially hazardous situation which, if not avoid- ed, will result in minor or moderate injury, or may result in seri- ous injury or death. Additionally there may be significant prop- erty damage.
Indicates a potentially hazardous situation which, if not avoid- ed, may result in minor or moderate injury, or in property dam- age.

Symbols

This section shows the safety symbols and alerts used in this manual.

In order to use FLOW iQ safely, the precautions listed in this manual are indicated by alert symbols. The descriptions associated with these symbols must be followed, failure to follow all precautions and alerts may result in an unsafe installation or operation. The following symbols are used in this manual.

	The circle and slash symbol indicates operations that you must not do. The specific operation is shown in the circle and explained in text. This example indicates prohibiting disassembly.
	The triangle symbol indicates precautions (including warnings). The specific operation is shown in the triangle and explained in text. This example indicates a precaution for electric shock.
$\underline{\land}$	The triangle symbol indicates precautions (including warnings). The specific operation is shown in the triangle and explained in text. This example indicates a general precaution.
0	The filled circle symbol indicates operations that you must do. The specific operation is shown in the circle and explained in text. This example shows a general precaution for something that you must do.

Warning

The Autonomous Mobile Robots (AMRs) monitored by FLOW iQ must be configured to operate with OMRON system operating software.



System and travel status parameters monitored by FLOW iQ are to be used for informational and planning purposes only and must not be used in safety-critical functions.

To maintain the security and reliability of the system, a robust cybersecurity defense program should be implemented, which may include some or all of the following: **Anti-virus protection**

- Install the latest commercial-quality anti-virus software on the computer connected to the control system and keep the software and virus definitions up-to-date.
- Scan USB drives or other external storage devices before connecting them to control systems and equipment.

Security measures to prevent unauthorized network access

- Install physical controls so that only authorized personnel can access control systems and equipment.
- Reduce connections to control systems and equipment via networks to prevent access from untrusted devices.
- Install firewalls to block unused communications ports and limit communication between systems. Limit access between control systems and systems from the IT network.
- Control remote access and adopt multifactor authentication to devices with remote access to control systems and equipment.
- · Set strong password policies and monitor for compliance frequently.

Data input and output protection

- · Backup data and keep the data up-to-date periodically to prepare for data loss.
- Validate backups and retention policies to cope with unintentional modification of input/ output data to control systems and equipment.
- Validate the scope of data protection regularly to accommodate changes.
- Check validity of backups by scheduling test restores to ensure successful recovery from incidents.
- Safety design, such as emergency shutdown and fail-soft operations in case of data tampering and incidents.

Additional recommendations

- When using an external network environment to connect to an unauthorized terminal such as a SCADA, HMI or to an unauthorized server may result in network security issues such as spoofing and tampering.
- You must take sufficient measures such as restricting access to the terminal, using a terminal equipped with a secure function, and locking the installation area by yourself.
- When constructing network infrastructure, communication failure may occur due to cable disconnection or the influence of unauthorized network equipment.
- Take adequate measures, such as restricting physical access to network devices, by means such as locking the installation area.
- When using devices equipped with an SD Memory Card, there is a security risk that a third party may acquire, alter, or replace the files and data in the removable media by removing or unmounting the media.
- Please take sufficient measures, such as restricting physical access to the Controller or taking appropriate management measures for removable media, by means of locking and controlling access to the installation area.
- Educate employees to help them identify phishing scams received via email on systems that will connect to the control network.

Cautions

A CAUTION





The administrator is responsible for the selection and training of personnel to properly in- stall, operate, and maintain FLOW iQ and the systems that it interfaces with.	0
The installation of the FLOW iQ application software requires proper configuration with existing OMRON applications. Verify that you have the correct operating permissions before attempting to install and use FLOW iQ.	0
FLOW iQ is a monitoring program and does not control the fleet of AMRs or any individu- al AMR.	0

Precautions for Safe Use

This section identifies the proper precautions for the safe use of FLOW iQ.

Make sure to follow all the safety precautions that are necessary to ensure safe use of the product.

- Thoroughly read this manual and understand the installation, operation checks, and maintenance procedures before using the product.
- Only use this product within the specified conditions and installation methods.
- Always install software and equipment that is included in the product specifications. Not doing so may result in failure or malfunction.
- Comply with all the laws, regulations, and standards of the country/region where the product is used.

Precautions for Correct Use

This section identifies the proper precautions for the correct use of FLOW iQ. Observe the precautions described below to prevent operational failure, malfunctions, or undesirable effects on product performance or fleet historical data.

- The Fleet Manager and associated software must be operating and licensed to use FLOW iQ.
- The user interface representations in this document were captured with a specific browser and version. The appearance may vary slightly from what is shown in this manual.
- The **Reset** Button in the *Fleet Operations Workspace iQ* SetNetGo area is used to reset the application to its default state. Clicking the **Reset** Button removes all configurations, fleet history, and stored data. This resets the application to a default, unconnected state.
- If the Queuing Manager is disabled, FLOW iQ will function normally, but no activity will be provided in the Job History page.
- Data representation in the Robot Status area may not appear accurately after downgrading an existing system from FLOW iQ v3.0. Contact your local OMRON representative for more information.
- The Integration Toolkit should be running with a generated password to utilize all FLOW iQ functions.

Regulations and Standards

FLOW iQ is a software application that operates within the Fleet Operating Workspace CORE software, residing in the Fleet Manager. The application displays data from within the Fleet Operating Workspace CORE software and does not control or alter the performance of the systems.

Software Licenses and Copyrights

This product incorporates certain third party software.

Related Manuals

Use the following related manuals for reference.

Related Product Manuals

Manual Name	Description
EM2100 Installation Guide (Cat. No. I634)	Describes the installation of the Fleet Manager.
Fleet Operation Workspace Core Integra-	Integration Toolkit is used to perform integration between the
tion Toolkit User's Manual (Cat. No. I637)	Fleet Manager and the end user's client application.
Fleet Operations Workspace Core User's	Contains information that is necessary for installing and configur-
Manual (Cat. No. l635)	ing an AMR fleet management and control system within a facility.
Fleet Simulator User's Manual (Cat. No. I649)	Describes the use of the Fleet Simulator.
HD-1500 Platform User's Manual (Cat. No. I645)	Describes the use of the HD-1500 Mobile Robot.
Mobile Robot LD Safety Guide (Cat. No. I616)	Describes the safety information for the LD mobile robots.
LD Platform Peripherals User's Guide (Cat. No. I613)	Describes the user of the LD Platform Peripheral equipment.
LD-60/90 Platform User's Manual (Cat. No. I611)	Describes the use of the LD Platform Mobile Robot.
LD-250 Platform User's Manual (Cat. No. I642)	Describes the use of the LD-250 Mobile Robot.
HD Mobile Robot Safety Manual (Cat. No. I647)	Describes the safety information for the HD-1500 mobile robots.

Glossary

Term	Definition	
Access Point	Physical location of wireless device	
AMR	Autonomous Mobile Robot	
API	Application Programming Interface	
BSSID	Basic Service Set Identifier; the MAC (Media Access Control) physical address of the access point	
Fault	Event where there may be an operating error with an AMR	
FLOW iQ	Abbreviated name for Fleet Operations Workspace iQ	
Мар	Graphic showing the particular boundaries and events for an AMR or AMR fleet	
Ping	Communication time between the AMR and the Fleet Manager	
Roam	An event, where the AMR switches to a different BSSID than the one currently connected to the network	
SSID	The Service Set Identifier which is the name of wireless network	

Revision History

On the front and back covers of the manual is a manual revision code, shown as a suffix to the catalog number.



Revision code	Date	Revised content
01	May 2021	Initial publication
02	March 2022	Updates for FLOW v2.2
03	December 2022	Updates for FLOW v3.0
04	October 2023	Updates for FLOW v4.0

User Interface

This section provides information about the FLOW iQ user interface.

1-1	Interfa	Interface Structure1-2							
1-2	Side B	ar	1-3						
1-3	Inform	ation Area	1-4						
1-4	Title B	ar							
	1-4-1	Date/Time	1-5						
	1-4-2	Language	1-6						
	1-4-3	User	1-6						
	1-4-4	License							
1-5	Menu I	3ar	1-7						
	1-5-1	Home	1-7						
	1-5-1 1-5-2	Home Robot Status							
		Home	1-8						
	1-5-2	Home Robot Status	1-8 1-8						
	1-5-2 1-5-3	Home Robot Status Job History							
	1-5-2 1-5-3 1-5-4	Home Robot Status Job History Battery Info							

1-1 Interface Structure

The FLOW iQ interface shows the operational information and status of an AMR or AMR fleet, using a combination of graphs, data tables and notifications. The views and presented data are controlled with the Title Bar, Menu Bar and selectable Additional Information within the pages.



Precautions for Correct Use

The user interface representations in this document were captured with a specific browser and browser version. The appearance may vary slightly from what is shown in this manual, depending upon the browser that is used.



ltem	Name	Description			
1	Title Bar	Date/Time setting, License Status, User ID, Language Selection.			
2	Menu Bar	Menu functions, API details, Download function.			
3	Additional Information	Select for additional information shown in the Information Area.			
4	Information Area	Graph or table showing AMR or fleet status.			
5	AMR Identification	Number and model of the AMRs in the fleet.			
6	Side Bar	Current details of the Information Area data.			

1-2 Side Bar

The *Robot Status* Side Bar provides the cumulative status within the current one-hour operating interval for the data displayed in the Information Area. The Side Bar for *Job History* and *Battery Info* displays non-cumulative data at 10 second intervals. Side Bar data displays when either fleet or an individual AMR is selected in Robot Status. The *Robot Status* Side Bar is shown in the following figure.



- --- -

1

1-3 Information Area

FLOW iQ provides both fleet and AMR operational data in both graphical and tabular format. The primary region of the browser that displays this data is the Information Area, shown in the following figure. The Information Area data is cumulative for the selected Date/Time interval. Refer to *Section 3 Operation* on page 3-1 for more information.



1-4 Title Bar



The Title Bar provides the following information.

Item	Description					
1	Title Bar					
2	Date and Time Selection Refer to <i>1-4-1 Date/Time</i> on page 1-5 for more information.					
3	Remaining days for license Refer to <i>1-4-4 License</i> on page 1-6 for more information.					
4	User Refer to <i>1-4-3 User</i> on page 1-6 for more information.					
5	Language Selection Refer to <i>1-4-2 Language</i> on page 1-6 for more information.					

1-4-1 Date/Time

The Date/Time shows the current day and time on the *Home* page. The Date/Time selection is editable when *Robot Status*, *Job History*, *Battery Info* or *Map* are selected. The options can be for a fixed time interval, such as a week or month, or another user specified interval. The Date/Time selection is a drop-down that may display differently in different browsers. Refer to *3-2-1 Date/Time Settings* on page 3-3 for more information.

Today	This Week	This Month	All Time
From 09/08/2022	To	8/2022 🛱 🕑	Add Shift Time
Start time	End tim		

1-4-2 Language

English is the default language for FLOW iQ. The information and graphs can display in 10 languages:

- German
- English
- Spanish
- French
- Italian
- Japanese
- Korean
- Polish
- Traditional Chinese
- Simplified Chinese

Change to a language other than English by left-clicking the arrow under the User name, and making the selection.

1-4-3 User

The name of the logged on user is fixed as *iquser* and is displayed at the top-right corner of the Title Bar.

1-4-4 License

The Title Bar displays the available FLOW iQ license period.

omr	RON Fleet (Operations Wo	rkspace iQ	1 T	oday, 10/05/2022 03:40 PM	Remaining days in license period: 365	iquser ∯ English w
Home	Robot Status	Job History	Battery Info	Мар	Wireless Diagnostics		API 📩

1-5 Menu Bar

The Menu Bar is the primary navigation feature in FLOW IQ. The Menu Bar has six selectable navigation items in addition to the API and Download functions.



1-5-1 Home

When FLOW iQ starts, the *Home* option of the Menu displays a current view of the fleet operation. Refer to *3-3 Home Functions* on page 3-9 and *3-1 Accessing FLOW iQ* on page 3-2 for more information.



ltem	Name	Description
1	Notifications	Completed jobs or errors and faults.

1

ltem	Name	Description
2	Live Map	Fleet operating area containing live information.
3	Job History	Summary of job activity.
4	Robot Status	Graph of AMR fleet operating activity.

1-5-2 Robot Status

Robot Status shows the performance and maintenance state of a fleet or individual AMR. The Information Area contains a dual level, pie chart graph that shows the status for a time interval selected with the Date/Time values. Refer to *3-4 Robot Status* on page 3-10 for more information.



ltem	Name	Description
1	Side Bar	Robot Status, current hour's status. Four major areas of interest: Charging, Working, Waiting and Error.
2	Fleet/AMR Selection	Enables data selection of the AMR fleet or an individual AMR.
3	Status Selection	Three options display the cumulative status as: a pie chart, bar graph or maintenance record (for individual ro- bots) during the selected time interval.
4	Status Detail	Displays the details of the selected status from the pie chart.
5	Substatus	Provides cumulative substatus information about dock- ing, docked, driving, at-goal, available, queued, discon- nected, emergency stop, and fault states. This area provides additional details for the main status area.
6	Main Status	Provides cumulative status information about charging, working, waiting, and error states.
7	AMR Identification	Number and model of fleet AMRs.

The *Historical Status* displays the same *Status Utilization* data, but as a line graph for the selected time interval.

The Maintenance Tab shows the operating records and software versions for a selected AMR.

1-5-3 Job History

Job History shows the work performance of a fleet or individual AMR. The Information Area bar graph shows the job results, for the selected time interval.

The bars of the graph show the cumulative job activity for the time interval identified along the bottom of the graph. The colors correspond to the job status shown on the Side Bar.

- Green: Completed
- Blue: In-progress
- Gray: Canceled jobs
- Red: Failed jobs.

Refer to 3-5 Job History on page 3-12 for more information.



Item	Name	Description		
1	Fleet/AMR Selection	Enables selection of the AMR fleet or an individual AMR.		
2	Graph/Segments & Jobs	Selector for the type of data presented, chart or tabular.		
3	Information Area	Graph or table presentation in this section.		
4	Side Bar	Cumulative status of the jobs over the defined time interval.		

The Segments & Jobs Tab for the Fleet shows the data in a table format with three areas of interest: *Most Used Segments, Most Failed Jobs, and Most Failed Robots.*

Home Robot Status Jo	b History	Battery Info	Мар	Wireless Diagnostics					_		API ±
Fleet Individual Robot 🔻	Gra	bh Segmen	ts & Jobs								
	Most	Used Segm	ents			Most Fa	illed Jobs		Most	Failed Robots	
072		GOAL		AVG TIME	GOAL		JOB	FAIL		ROBOT	FA
フノ 二 Total Jobs	1	T1-02		0m 18s	T2-02	ï	J0B401	585	ï	Sim19	51
	2	T3-02		0m 48s	T3-04	2	J0866	45	2	Sim14	
	3	T1-05		0m 18s	T2-05	3	IQJun72022-17	1	3	Sim13	
958 Completed	4	T1-01		0m 18s	T2-01	4	IQJun72022-371	1	4	Sim7	
Average Job Time: 6m 29s	5	B1-01		0m 0s	B2-01	5	IQJun72022-399	1	5	Sim8	
0 In Progress	٥	T3-04		0m 43s	T3-02	0	IQJun72022-397	1	٥	Sim10	
	7	T3-01		0m 51s	T3-05	7	IQJun72022-403	1	7	Sim11	
0 Cancelled	8	T3-03		1m 9s	T3-01	8	IQJun72022-146	1			
14 Failed	9	T1-03		9m 1s	T2-03	9	J0842	1			
	10	T3-05		1m 11s	T3-01	10	J08365	1			

The Segments & Jobs Tab for an individual AMR shows the data in a table format with three areas of interest: *Most Used Segments, Completed Jobs,* and *Failed Jobs.*

1

Home Robot Status	Job History Battery	info Map \	Vireless Diagnostics						AM 🛨
Fleet Sim7									
	Graph Se	egments & Jobs							
	Most Used S	egments		Co	mpleted Jobs		Failed	d Jobs	
102	GOAL	AV	G TIME GC	DAL	JOB	DATE & TIME		JOB	FAILUF
Total Jobs	1 T3-03	1m	9s T3	101 1	J08627	9/14/2022, 4:40:20 PM	1	QJun72022-146	
	2 T1-05	Om	16s T2	905 2	J08621	9/14/2022, 4:37:46 PM	2	QJun72022-371	
	3 B3-03	Om	598 B3	I-01 3	J08625	9/14/2022, 4:37:22 PM	3	J08365	
9 Completed	4 81-02	Om	14s B2	-02 4	J08605	9/14/2022, 4:36:03 PM			
erage Job Time: 7m 20s	5 B3-01	Om	24s B3	1-05 5	J08577	9/14/2022, 4:33:42 PM			
In Progress	6 T1-01	Om	16s T2	-01 6	J08547	9/14/2022, 4:27:28 PM			
	7 B1-01	Orr	Os B2	-01 7	J08515	9/14/2022, 4:24:57 PM			
Cancelled	8 T1-02	Om	15s T2	-02 8	J08551	9/14/2022, 4:24:26 PM			
Failed	9 Goal75	Om	14s Go	sal79 9	J0B489	9/14/2022, 4:23:52 PM			
	10 B1-05	Om	15s B2	-05 10	J08341	9/14/2022, 4:18:01 PM			
				11	J08349	9/14/2022, 4:15:52 PM			
				12	J08353	9/14/2022, 4:15:27 PM			
				13	J08411	9/14/2022, 4:13:26 PM			
				14	J08365	9/14/2022, 4:11:08 PM			
				15	J0B437	9/14/2022, 4:10:23 PM			
				16	J0B387	9/14/2022, 4:09:17 PM			
				17	J08335	9/14/2022, 4:08:04 PM			
				18	J0B305	9/14/2022, 3:32:50 PM			

1-5-4 Battery Info

Battery Info shows the battery and power performance of a fleet or individual AMR. The Information Area line graph shows the cumulative battery and AMR performance, for the selected time interval. Refer to *3-6 Battery Info* on page 3-14 for more information.



Item	Name	Description
1	Fleet/AMR Selection	Enables selection of the AMR fleet or an individual AMR.
2	Performance Details	Selectable tabs that display the performance of AMR and battery parameters graphically.
3	Information Area	Shows cumulative, battery power or performance over a selected time interval.
4	Side Bar	Current status of the Battery Performance Details in both numeric and qualitative values (if known) are shown.

1-5-5 Map

The *Map* is a graphical representation of the operating area for the AMR fleet. Limiting boundaries and obstacles are shown with the cumulative paths of the operating AMRs. Refer to *3-7 Map* on page 3-15 for more information.



Item	Name	Description
1	Fleet/AMR selection	Enables selection of the AMR fleet or an individual AMR.
2	Time Progression	Displays cumulative operation for the defined time interval.
3	Information Area	The physical and operating boundary for AMRs.
4	Map Selection	Displays specific maps from a selection of four options.
5	Fault Selection	Toggle to identify selectable faults and selected AMR categories.
6	Map Settings	Optional selections to display data.
7	Display Controls	Zoom, view and reset controls for the map view.

The Map Selection drop-down has four data display options:

- Position Density Map: Displays frequency an AMR passed through a grid location.
- Localization Map: Shows the cumulative localization score reported by the AMR.
- Wireless Quality Map: Displays the Wireless signal strength for the AMR travel points.
- Floor Map: Displays the boundary of fleet operations and obstacles.

1-5-6 Wireless Diagnostics

Flow 4.0 is expanded to include a more detailed analysis of an AMR Fleet's wireless status to improve wireless performance. Wireless Diagnostics shows the AMRs interactions with access points, roaming, signal strength, and channel interference. Refer to *3-8 Wireless Diagnostics* on page 3-17 for more information.



1

ltem	Name	Description
1	Show/Hide panel	Opens side panel for an overview of all connected and detected but not
		connected networks.
2	Signal	Shows the signal level in dbm for map.
3	Ping	Displays time interval between the AMRs and Fleet Manager.
4	BSSIDs	Identifies a physical access point locations where AMRs have the abili-
		ty to connect.
5	Other	Displays additional networks that are not connected to the selected
		AMR.
6	Roams	Identifies BSSID switching regions.

1-5-7 API and Download

The FLOW iQ API shows the current operating API parameters. Refer to 3-9-1 API Operation on page 3-22 for more information.

OMRON			Fleet Operations Workspace iQ \rightarrow
	The Flow ID APP allows clients to get different types of data from their Mobile Robots.		
	Sever Flowing- Seve path on Entropyline Manager 🗳		
	Battery	^	
	GET /api/v1/battery-info	\sim	
	GCI /api/v1/battery-info/all	\sim	
	GEI /api/vl/battery-info/charging	~	
	GET /api/v1/battery-info/live	\sim	
	GEI /api/v1/battery-info/robots	~	
	GET /api/v1/battery-threshold	\sim	

The **Download** Icon ($\stackrel{\bullet}{\frown}$) saves the Information Area in either of three formats: pdf, png or jpg. Refer to 3-9-2 *Download* on page 3-24 for more information.

2

Installation

This section provides information about the installation of FLOW iQ.

2-1	Instal	lation Steps	
2-2	Versio	on Conflicts	2-4
2-3	Resto	ore Default Settings	2-5
2-4	Licen	sing	2-7
	2-4-1	License Details	
	2-4-2	License Installation	

2-1 Installation Steps

FLOW iQ is included in FLOW Core v2.2 and above. Use the following procedure if FLOW iQ is not included in your version of FLOW Core or when FLOW iQ needs to be upgraded.

Upgrading FLOW Core can impact AMR operations and functionality. Refer to the *Fleet Operations Workspace Core User's Manual (Cat. No. 1635)* or contact your local OMRON representative for more information.

- The installation of the FLOW iQ application software requires proper configuration with existing OMRON applications. Verify that you have the correct operating permissions before attempting to install and use FLOW iQ
- The administrator is responsible for the selection and training of personnel to properly install, operate, and maintain FLOW iQ and the systems that it interfaces with.



Precautions for Safe Use

Only use this product within the specified conditions and installation methods.

- Always install software and equipment that is included in the product specifications. Not doing so may result in failure or malfunction.
- Comply with all the laws, regulations, and standards of the country/region where the product is used.



Precautions for Correct Use

The Integration Toolkit should be running with a generated password to utilize all FLOW iQ functions.

1 Open a browser and enter the Fleet Manager IP in the address field to access SetNetGo.

	Status	Network	Software	Integration	Licensing	Security	System	
							Download debug info	Refresh
Home								
ARAMCentral Log Network				Mode of	Operation:	Standalone	Fleet Manager	
SetNetGo Log				Mainten	ince Ethernet:	Disconnect	ed	
SetNetGo Resources			1877 N 27 19	Manager	nent Interface:	Connected		
Debug Info				Manage	nent Interface IP:	10.151.26.	180	
				Fleet IP:		10.151.26.	181	
				System	Jptime:	22 hours 4	7 min	

2 Access the **Software** area in SetNetGo and then select **Manage Installed Software**.

- **3** Click the **Browse** Button, navigate to the Fleet_Operations_Workspace_Core_X.X.X.targ.gz file, and select it (X.X.X represents the version of the FLOW Core package).
- **4** Click the **Open** Button and then confirm that the correct file is displayed in SetNetGo.

								English	✓ EMANAGER
	Status	Network	Software	Integration	Licensing	Security	System		
Manage Installed				Install Software:	Browse Flee	t_Operations_Wo	orkspace_Core_	_3.0.0.tar.gz	Upload

2-1 Installation Steps

- **5** Click the **Upload** Button to begin the FLOW Core installation process.
- **6** After the intallation process is complete, expand the Fleet Operations Workspace iQ item in the *Manage Installed Software* area.

Fleet Operations Workspace IQ provides insight into the fleet and AMR operation by collecting, processing, and visualizing data.	Fleet Operations Workspace iQ	3.0.0	Enabled Running
Warning! This nackage was originally installed as nart of the software suite but subsequently overwritten		s insight into the fleet and AM	R operation by collecting, processing, and
Varning! This nackage was originally installed as part of the software suite, but subsequently overwritten			

7 Confirm that the FLOW iQ application is running.

Fleet Operations Workspace iQ	3.0.0	Enabled Running	~
Fleet Operations Workspace iQ provides in visualizing data.	nsight into the fleet and AM	IR operation by collecting, processing,	and
Warning! This package was originally ins	talled as part of the softw	rare suite, but subsequently overwr	itten.
View Release Notes View Runtime Log	Restart Disable Re	eset	

If FLOW iQ is not running, click the **Restart** Button in the *Fleet Operations Workspace iQ* area. Correct FLOW iQ operation is dependent on the Integration Toolkit.

If FLOW iQ is not running after restarting, check the status of the Integration Toolkit. If the Integration Toolkit is not running, click the **Restart** Button. After the Integration Toolkit has restarted and is running, click the **Restart** Button in the *Fleet Operations Workspace iQ* area again.

8 A new password must be generated for FLOW iQ. The Integration Toolkit password must be generated prior to attempting to generate the FLOW iQ password. If the Integration Toolkit password has not been generated, access the SetNetGo > Security > Integration Toolkit area and click the Generate New Password Button before generating a password for FLOW iQ. To generate a new password for FLOW iQ, click the Generate New Password Button in SetNetGo > Security > FLOW iQ and save this system generated password. The installation process is complete after the new password is generated.

2-2 Version Conflicts

An error message will be displayed when starting FLOW iQ if there is a version conflict.

Fleet Operations Worksp	bace iQ 🛱 Today, 09/19/2022 03:25 PM	iquser 😚 English 👻
Home Robot Status Job History Ba	attery info Map	API 🛨
Notifications WAITING FO	C Live Map Projected and Previous Paths Version Mismatch! Flow IQ has detected a SNG version prior to 7.0.0 (Flow 3.0 SNG version) - Flow IQ will lose live data and other functionality until SNG has been upgraded.	:: £
Robot Status 🖸 🖸	Clese O Total Jobs	? +

When the pop-up is closed the 🖸 icon displays on the top right of FLOW iQ. To use the Wireless

Diagnostic feature, the Flow4.0 package must be uploaded to each AMR in the fleet.

Refer to *Requirements* on page 1 or contact your local OMRON representative for more information about version conflicts.
2-3 Restore Default Settings

The following procedure describes how to restore FLOW iQ to factory default settings.

ďЪ	P

Precautions for Correct Use

The **Reset** Button in the Fleet Operations Workspace iQ SetNetGo area is used to reset the application to its default state. Clicking the **Reset** Button removes all configurations, fleet history, and stored data. This resets the application to a default, unconnected state.

1 Open a browser and enter the Fleet Manager IP in the address field to access SetNetGo.

	Status	Network	Software	Integration	Licensing	Security	System	
			6				Download debug info	Refres
Home							Sourced debug me	Trenes
ARAMCentral Log								
Network				Mode of	Operation:	Standalone	e Fleet Manager	
SetNetGo Log				Mainten	ance Ethernet:	Disconnec	ted	
SetNetGo Resources			10 10 10 10 10	Manager	ment Interface:	Connected		
Debug Info				manage	inchi internater.	Gonnected		
				Manage	ment Interface IP:	10.151.26.	180	
				Fleet IP:		10.151.26.	181	
				System	Uptime:	22 hours 4	7 min	

2 Access the **Software** area as shown below.

						ID:	English V
	Status Network	Software	Integration	Licensing	Security	System	
Manage Installed Software ARAMCentral Settings Simulator	Fleet_Operations_	tware Versi	2.0.1	install Software: (Choose File No	o file chosen	Upload
Automatic Updates Debug Replay	ARAMCentral ARAMCentral is View Release N	the software that pro	5.4. ovides the main fu		Enterprise Mana	ger.	
	MobileFirmware Firmware updat	e for low level robot		0-RC1-2020080	4192617 N	ot Running	
	View Release N	View Runtin	me Log Restart				
	Call/Door Box S	oftware	3.0	.3	D	isabled Not Run	ning >
	DefaultConfig		1.2	.3			>



RAMCentral Settings					
Simulator	Fleet_Operations_Works	space_Core_2.0.1-INTERNA	L6 (View Suite Conte	ents)	
Indiator	ARAMCentral	5.4.2			
utomatic Updates	ARAMCentral is the sol	Itware that provides the main fund	tionality for an Enterpris	e Manager.	
ebug Replay			,	<u>,</u>	
long replay					
	View Release Notes	Restart			
	MobileFirmware	1.0.0	-RC1-20200804192617	Not Running	
	Firmware update for lo	w level robot control			
	View Release Notes	View Runtime Log Restart			
	View Release Notes	View Runtime Log Restart			
	View Release Notes			Disabled Not Running	>
				Disabled Not Running	>
	Call/Door Box Software DefaultConfig	e 3.0.3 1.2.3			
	Call/Door Box Software DefaultConfig Fleet Operations Work	e 3.0.3 1.2.3 space iQ 1.0.0		Enabled Running	>
	Call/Door Box Software DefaultConfig Fleet Operations Work	e 3.0.3 1.2.3		Enabled Running	>
	Call/Door Box Software DefaultConfig Fleet Operations Work Fleet Operations Work	e 3.0.3 1.2.3 space iQ 1.0.0		Enabled Running	>
	Call/Door Box Softwar DefaultConfig Fleet Operations Work Fleet Operations Work visualizing gata.	e 3.0.3 1.2.3 space iQ 1.0.0		Enabled Running	>
	Call/Door Box Softwar DefaultConfig Fleet Operations Work Fleet Operations Work visualizing gata.	e 3.0.3 1.2.3 space iQ 1.0.0		Enabled Running	>
	Call/Door Box Softwan DefaultConfig Fleet Operations Work Fleet Operations Work visualizing data.	e 3.0.3 1.2.3 space IQ 1.0.0 ispace IQ provides insight into the	fleet and AMR operation	Enabled Running	>
	Call/Door Box Softwar DefaultConfig Fleet Operations Work Fleet Operations Work visualizing gata.	e 3.0.3 1.2.3 space iQ 1.0.0		Enabled Running	>
	Call/Door Box Softwan DefaultConfig Fleet Operations Work visualizing data.	e 3.0.3 1.2.3 space IQ 1.0.0 ispace IQ provides insight into the	fleet and AMR operation	Enabled Running	>

4 Click the **Reset** Button in the *Fleet Operations Workspace iQ* area.

	Mobile Software	Version:		
ARAMCentral Settings				
imulator	Fleet_Operations_Workspa	ace_Core_2.0.1-INTERNAL6 (View S	uite Contents)	
	ARAMCentral	5.4.2		
utomatic Updates	ARAMCentral is the softwa	are that provides the main functionality for a	n Enterprise Manager.	
ebug Replay				
	View Release Notes F	Restart		
	The second second	1.0.00		
	MobileFirmware	1.0.0-RC1-202008	304192617 Not Running	
	Firmware update for low I	evel robot control		
	View Release Notes	/iew Runtime Log Restart		
	Call/Door Box Software	3.0.3	Disabled Not Running	>
			Disabled Not Running	>
	Call/Door Box Software	3.0.3	Disabled Not Running Enabled Running	
	Call/Door Box Software DefaultConfig Fleet Operations Workspi	3.0.3	Enabled Running	>
	Call/Door Box Software DefaultConfig Fleet Operations Workspr Fleet Operations Workspr visualizing data.	3.0.3 1.2.3 ace IQ 1.0.0	Enabled Running	>
	Call/Door Box Software DefaultConfig Fleet Operations Workspr Fleet Operations Workspr visualizing data.	3.0.3 1.2.3 ace IQ 1.0.0 ace IQ provides insight into the fleet and Alv	Enabled Running IR operation by collecting, processing, and	>
	Call/Door Box Software DefaultConfig Fleet Operations Workspervisualizing data. View Release Notes	3.0.3 1.2.3 ace IQ 1.0.0 ace IQ provides insight into the fleet and Alv /iew Runtime Log Restart Disable	Enabled Running IR operation by collecting, processing, and Reset	~

After clicking the **Reset** Button, this procedure is complete, resetting both FLOW iQ and the database.

2-4 Licensing

FLOW iQ software access requires a valid, time-based license unless the Fleet Manager is in Fleet Simulator mode. If the license expires, access to the FLOW iQ software is prohibited but FLOW iQ continues to record data.

For versions of FLOW iQ after v2.0, FLOW iQ licenses must be purchased.

2-4-1 License Details

The Title Bar displays the remaining time for the FLOW iQ license once it is properly activated. This information displays on the right-side of the Title Bar.

OMRC	Fleet C	perations Wo	rkspace iQ	i 1	oday, 10/05/2022 03:40 PM	Remaining days in license period: 365	iquse S English v
Home	Robot Status	. Job History	Battery Info	Man	Wireless Diagnostics		API 🔸

When the license is at or under the 30 day remaining limit, a warning displays above the Title Bar, showing the remaining days for the license.

						Remaining days in license period: 22		
Ī	OMR	ON Fleet C	perations Wo	orkspace iQ	ā	Today, 10/04/2022 01:55 PM Remaining days in license period: 22	i 😚 Engl	iquser lish ▼
	Home	Robot Status	Job History	Battery Info	Мар	Wireless Diagnostics	API C-D	+

Contact your Omron representative for license information when this warning is displayed.

Precautions for Correct Use

The Fleet Manager and associated software must be operating and licensed to use FLOW iQ.

2-4-2 License Installation

The FLOW iQ license installation is accomplished using SetNetGo. The procedure is similar to other FLOW license installations. Refer to the *Fleet Operations Workspace Core User's Manual (Cat. No. 1635)* for more information.

If FLOW iQ was not licensed and functional prior to the installation, it should be manually restarted to immediately activate a new license. If FLOW iQ is not restarted, it will automatically activate within 24 hours.

3

Operation

This section provides information about FLOW iQ operation.

3-1	Acces	ssing FLOW iQ	3-2
3-2	Comm 3-2-1 3-2-2	non Operations Date/Time Settings Map View Controls	3-3
3-3	Home	Functions	3-9
3-4	Robot	Status	3-10
	3-4-1 3-4-2	Fleet Status Individual Robot Status	3-10
3-5	Job Hi	istory	
•••	3-5-1	Job History Graph	
	3-5-2	Job History Segments & Jobs	
3-6	Batter	ry Info	3-14
	3-6-1	Battery Info Graphs	
3-7	Мар		3-15
	3-7-1	Position Density Map	
	3-7-2	Localization Map	3-15
	3-7-3	Wireless Quality Map	
	3-7-3 3-7-4	Wireless Quality Map Floor Map	
3-8	3-7-4		3-16
3-8	3-7-4	Floor Map	3-16 3-17
3-8	3-7-4 Wirele	Floor Map	3-16 3-17 3-17
3-8	3-7-4 Wirele 3-8-1 3-8-2 3-8-3	Floor Map Signal Ping BSSID	
3-8	3-7-4 Wirele 3-8-1 3-8-2 3-8-3 3-8-3 3-8-4	Floor Map ess Diagnostics Signal Ping BSSID Other	3-16 3-17 3-17 3-18 3-18 3-19
3-8	3-7-4 Wirele 3-8-1 3-8-2 3-8-3	Floor Map Signal Ping BSSID	3-16 3-17 3-17 3-18 3-18 3-19
3-8	3-7-4 Wirele 3-8-1 3-8-2 3-8-3 3-8-4 3-8-5	Floor Map ess Diagnostics Signal Ping BSSID Other	
	3-7-4 Wirele 3-8-1 3-8-2 3-8-3 3-8-4 3-8-5	Floor Map Signal Ping BSSID Other Roams	

3-1 Accessing FLOW iQ

The FLOW iQ interface can be accessed with a web browser using the following URL.

https://[IP]/FlowIq

IP represents the SetNetGo Fleet IP address found in the area shown below.

The Username is "iquser". Use the password that was generated in SetNetGo (refer to 2-1 Installation Steps on page 2-2 for more information.

	Status	Network	Software	Integration	Licensing	Security	System	
Home			3				Download debug info	Refresh
ARAMCentral Log								1
Network				Mode of	Operation:	Standalone	e Fleet Manager	
SetNetGo Log				Mainten	ance Ethernet:	Disconnect	led	
SetNetGo Resources			11 1 12 13 13 14	Manager	nent Interface:	Connected		
Debug Info				Manage	ment Interface IP:	10.151.26.	180	
				Fleet IP:		10.151.26.	181	
				System	Uptime:	22 hours 4	7 min	

Precautions for Correct Use

The Integration Toolkit should be running with a generated password to utilize all FLOW iQ functions.

3-2 Common Operations

This section provides information to use operations common to all functions of FLOW iQ.

- System and travel status parameters monitored by FLOW iQ are to be used for informational and planning purposes only and must not be used in safety-critical functions.
- The Autonomous Mobile Robots (AMRs) monitored by FLOW iQ must be configured to operate with OMRON system operating software.

3-2-1 Date/Time Settings

Change the time interval for the FLOW iQ displayed data using the following procedures.

Calendar Settings

Use the following procedure to define a time interval for review.

- **1** Select any Menu item other than *Home*.
- 2 Left-click the arrow next to the Date/Time on the Title Bar to display the drop-down calendar and time interval.



- **3** Select a time interval from the fixed options of *Today*, *This Week*, *This Month*, or *All Time*.
- **4** Set a specific time interval by left-licking the *From* and *To* calendars and selection a day from each to set the interval.
- **5** Left-click in the FLOW iQ application to close the calendar and view the results of the set interval.

The selected range shows in the Date/Time part of the Title Bar. The FLOW iQ display updates, showing the AMR or fleet activity within that selected interval. The update applies to all the Menu options until it is changed.

Shift Settings

Use the following procedure to define a specific shift to display.



Additional Information

The entire day will be displayed if Shift Settings are not set.

- **1** Select any Menu item other than *Home*.
- **2** Left-click the arrow next to the Date/Time on the Title Bar to display the drop-down calendar and time interval.
- **3** Select a time interval from the fixed options, or manually set the interval from the calendar.
- **4** Click the **Check box** next to *Add Shift Time*, opening the shift selection.



5 Left-click the **Start Time** and **End Time** drop-downs and select the start and end shift hours. The update applies to all the Menu options until it is changed.

3-2-2 Map View Controls

Maps have common view controls, allowing users to display the graphic to obtain the maximum information from each map.



FLOW iQ is a monitoring program and does not control the fleet of AMRs or any individual AMR.





Item	Name	Description
1	Time Progression	Displays AMR or fleet status for the defined time interval using the Start and Pause buttons.
2	Information Area	Physical and operating boundary for AMRs. Displays path of an AMR or the AMR fleet, as selected.
3	Map Selection	Displays specific map from a selection of four options, to view the selec- tion options for the same time interval. Refer to <i>Map Selection</i> on page 3-5 for more information.
4	Fault Selection	Toggle to identify selectable faults and selected AMR categories for each map. Refer to <i>Fault Selection</i> on page 3-5 for more information.
5	Map Settings	Optional selections to display data: Grid, Legend, Goals, Smooth Data, Dimensions. Refer to <i>Map Settings</i> on page 3-6 for more information.
6	Display Controls	Zoom and reset controls of map view. Refer to <i>Display Controls</i> on page 3-7 for more information.

Map Selection

FLOW iQ has four maps that are displayed from the Map Selection. When **Map** is selected from the Menu, the Fleet Position Density map opens as the default. Confirm the Date/Time for the data review, and whether a single AMR or the fleet map will be displayed. The same Date/Time and AMR/fleet values apply to all selected maps.

Click the Map Selection drop-down to select a different map from the four available options. The Time

Progression slider starts by clicking the arrow (🕨). Pause the Time Progression by clicking the rec-

tangle ().

Additional Information

The Time Progression will automatically run every time a map is selected.

Fault Selection

The FLOW iQ Fault Selection shows the fault location on the map and opens a table listing the details for each fault .

To use the Fault Selection, open any map and click the **Fault** Icon (^S). The Fault Table opens next to the map. The table shows all the faults for the selected time interval.

Use the *Select Categories* drop-down to select and display only specific faults in the table. Click the **All** drop-down to select between *Active*, *Inactive* and *All* AMRs.



When the *Fault* Icon is selected in one map, any other map that is opened also shows the faults and table. Click a fault in the table to highlight the location on the map. Click any mapped fault location to view the details in the table.

Map Settings

FLOW iQ maps have five settings. To use the settings, select any map and click the Settings Icon

(). The drop-down has five labeled check boxes for the settings. When selected, the map shows that setting option, and they persist for every map. Select or deselect the settings as needed to view specific map data.



Item	Item Setting Description			
1	Settings	Opens map display settings.		
2	Grid	Displays a grid matrix in the map Information Area.		

ltem	Setting	Description
3	Legend	The Legend color bar correlates to the relative frequency of an event. The values are normalized between 0 and 100. 100 is relative to the maximum frequency of all values, not a frequency of 100.
4	Goals	Goals are preset within the map area. Goals are most visible in the Floor Map. Re- fer to <i>Fleet Operations Workspace Core User's Manual (Cat. No. 1635)</i> for more information.
5	Smooth Data	Averages the data points for less defined data paths.
6	Dimensions	Shows a reference dimension for use with the map.

Display Controls

The FLOW iQ maps have display controls to improve viewing and understanding of the fleet or AMR data. The map controls are on the lower right-side of the map.



+

Use the magnification controls (

magnified by clicking the cursor over any map area and rolling the mouse wheel.

The map can also be rotated while holding the Control (Ctrl) key and left mouse button while moving the mouse. Hold the Ctrl key, left-click and hold the mouse button to rotate the map, to tilt the map at an angle.

When the map is angled, the relative bar height shows the value or frequency in that particular grid, as shown in the following figure.



Click the **Reset** Icon (\bigcirc) to return the map to a default magnification and orientation.

3-3 Home Functions

This section describes the use of the Home page.

The Home page has four sections showing the current status of the fleet: *Notifications, Robot Status, Job History* and the *Live Map*.



The *Notifications* view provides a limited, single line statement for job completion and errors or faults with operating AMRs. Click on a notification and the robot that completed this job or fault will be highlighted on the *Live Map*.

Expand Notifications, Live Map, and Robot Status by clicking the Expand icon (1) and reduce them

by clicking the **Reduce** icon (

Click the **Selection** icon (²) on the *Live Map*, *Job History*, or *Robot Status* to open the different views of each section.

The *Live Map* selected views are: *Robots Only, Previous Paths (green), Projected Paths (blue)*, and *Projected and Previous Paths.* The *Job History* views are the Current jobs and the Side Bar data. *Robot Status* views are the current Information Graphic and the Side Bar data for the fleet.

3

3-4 Robot Status

This section describes how to access and view Robot Status information.



Precautions for Correct Use

Data representation in the Robot Status area may not appear accurately after downgrading an existing system from FLOW iQ v3.0. Contact your local OMRON representative for more information.

3-4-1 Fleet Status

The following information applies to both the Fleet Status and Robot Status options.

When Robot Status is selected from the Menu, the application opens to the *Status Utilization* view of the fleet. Refer to *1-5-2 Robot Status* on page 1-8 for more information. Accept the default time, or change it to a specific interval. Refer to *3-2-1 Date/Time Settings* on page 3-3 for more information.



Hover the cursor over a specific area of the pie chart to view a pop-up with the exact values. Left-click a segment of the chart to display the Status Detail of that segment.

Click the **Historical Status** option to view the data in a line graph format for the time interval. The default graph shows four options: *Charging*, *Working*, *Waiting*, *Error*.



Click the **All Statuses** Drop-down and select a specific view from the four options: *Compare Charging*, *Compare Working*, *Compare Waiting*, and *Compare Failed*. Hover the cursor over a line and a pop-up opens, showing the status at that particular time.

The *Maintenance* Tab is inactive for a Fleet Status selection, and is activated after making the *Individual Robot* selection.

3-4-2 Individual Robot Status

The Side Bar, Information Area, Status Utilization and Historical Status options with Individual Robot status all function the same as with the Fleet status selection.

Click the **Individual** Drop-down to select the AMR of interest. Click the **Maintenance** Tab to view the data for the selected AMR. Refer to *3-2 Common Operations* on page 3-3 for information about the display and operating controls.

Home Robot Status	Job History	Battery I	nfo	Мар	Wireless Di	agnostics	
Fleet Sim10 Furrent Robot Status 9/27/22	Sta	tus Utilizatio	on ł	Historica	I Status	Maintenance	
86.67% Charging 86.67% Docked 0% Docking 13.21% Working 13.21% Driving 0% At Goal	0	0 0	62	. 9	97 km	ARAM Version: SNG Version: ARAM Uptime: CPU Use:	6.1.1 EnterpriseManager-7.0.0-beta.1 12 days 12.6885
0.13% Waiting 0.13% Available 0% Queued 0% Error 0% Disconnected							

3-5 Job History

This section describes how to access and view Job History information.



Precautions for Correct Use

If the Queuing Manager is disabled, FLOW iQ will function normally, but no activity will be provided in the Job History page.

3-5-1 Job History Graph

View the job performance over time by clicking **Job History** from the Menu. The page opens to the default *Fleet* view, and shows the performance as colored bar graphs. Accept the default, current date or click the **Date/Time** Drop-down to select the desired time interval. Refer to *3-2-1 Date/Time Set-tings* on page 3-3 for more information.



Hover the cursor over a point on any bar to open a pop-up, identifying the status, number of effected jobs and the date. Click **Individual Robot** and select an AMR, to view the same time interval graph for that single AMR.

3-5-2 Job History Segments & Jobs

View Job History, *Segments & Jobs* by clicking **Job History**, and then click the **Segments & Jobs** Tab. The page opens showing the same data as the Job History graph, but in table format.

Home Robot Status Je	ob History	Battery Info	Мар	Wireless Diagnostics							都 초
Fleet Individual Robot 🔻	Gra	bh Segmen	its & Jobs								
	Most	Used Segm	ents			Most F	ailed Jobs		Most	Failed Robots	
072		GOAL		AVG TIME	GOAL		JOB	FAIL		ROBOT	EA
J/Z Total Jobs	1	T1-02		0m 18s	T2-02	1	J08401	585	1	Sim19	5
	2	T3-02		0m 48s	T3-04	2	J0866	45	2	Sim14	
	3	T1-05		0m 18s	T2-05	3	IQJun72022-17	1	3	Sim13	
58 Completed	4	T1-01		0m 18s	T2-01	4	IQJun72022-371	1	4	Sim7	
rage Job Time: 6m 29s	5	B1-01		Om Os	B2-01	5	IQJun72022-399	1	5	Sim8	
In Progress	6	T3-04		0m 43s	T3-02	6	IQJun72022-397	1	6	Sim10	
	7	T3-01		0m 51s	T3-05	7	IQJun72022-403	1	7	Sim11	
Cancelled	8	T3-03		1m 9s	T3-01	8	IQJun72022-146	1			
4 Failed	9	T1-03		9m 1s	T2:03	9	J0B42	1			
	10	T3-05		1m 11s	T3-01	10	J08365	1			

The Side Bar shows the current status of the jobs performed during the defined time frame. Hover the cursor over any line in the *Most Used Segment* column to view the details pop-up. Click a blue Job Number in the *Completed Jobs* column to open the details for that job.

JOB621	JOB621-63223a7a		 ×
Status: Start Time:	Completed 9/14/2022, 4:32:58 PM	Start Charge: End Charge:	
Robot:	Sim7		

Click the Robot name in the pop-up to view the Most Failed Jobs pop-up for that AMR.

Sim7		>
100	Status: Charging::Docked Battery:	Robot Job History
Total Jobs	Most Failed Jobs	
	1 IQJun72022-146 1	
99 Completed Average Job Time: 7m 20s	2 IQJun72022-371 1	
0 In Progress	3 JOB365 1	
0 Cancelled		
3 Failed		
h		

Click the **Robot Job History** Button to view the job history for that AMR for the selected time interval. Click the *Robot* name in the *Most Failed Robots* column to view the *Most Failed Jobs* pop-up for that AMR. Then, click the **Robot Job History** Button to open the job history for that AMR. Click the **Individual** option and select an AMR, to open its Jobs & Segments view.

Home Robot Status	Job History	Battery Info	Мар	Wireless Diagnosti	cs						88 *
Fleet Sim7	• G	raph Segmer	nts & Jobs								
100	Mo	st Used Segm		AVG TIME	GOAL	Cor	pleted Jobs	DATE & TIME	Fail	ed Jobs	FAILURES
102	1	T3-03		1m 9s	T3-01	1	J08	9/14/2022, 4:40:20 PM	1	IQJun72022-146	PAILURES
Total Jobs	2	T1-05		0m 16s	T2-05	2	J08621	9/14/2022, 4:37:46 PM	2	IQJun72022-371	
	3	B3-03		0m 59s	83-01	3	J08625	9/14/2022, 4:37:22 PM	3	J08365	
	4	81-02		0m 14s	82-02	4	J08605	9/14/2022, 4:36:03 PM			
9 Completed rerage Job Time: 7m 20s	5	B3-01		0m 24s	B3-05	5	J08577	9/14/2022, 4:33:42 PM			
In Progress	6	T1-01		0m 16s	T2-01	6	J08547	9/14/2022, 4:27:28 PM			
	7	B1-01		Om Os	B2-01	7	J08515	9/14/2022, 4:24:57 PM			
Cancelled	8	T1-02		0m 15s	T2-02	8	J08551	9/14/2022, 4:24:26 PM			
Failed	9	Goal75		0m 14s	Goal79	9	J0B489	9/14/2022, 4:23:52 PM			
	10	B1-05		0m 15s	B2-05	10	J08341	9/14/2022, 4:18:01 PM			
						11	J08349	9/14/2022, 4:15:52 PM			
						12	J08353	9/14/2022, 4:15:27 PM			
						13	J08411	9/14/2022, 4:13:26 PM			
						14	J0B365	9/14/2022, 4:11:08 PM			
						15	J0B437	9/14/2022, 4:10:23 PM			
						16	J0B387	9/14/2022, 4:09:17 PM			
						17	J08335	9/14/2022, 4:08:04 PM			
						18	JOB305	9/14/2022, 3:32:50 PM			

Hover the cursor over any line in the *Most Used Segment* column to view the details in a pop-up for the selected segment.

Click a blue Job Number in the Completed Jobs column to open the details for that job.

JOB621-63223a7a			×
Completed	Start Charge:	74.93%	
9/14/2022, 4:32:58 PM	End Charge:	74%	
Sim7			
	Completed 9/14/2022, 4:32:58 PM	Completed Start Charge: 9/14/2022, 4:32:58 PM End Charge:	Completed Start Charge: 74.93% 9/14/2022, 4:32:58 PM End Charge: 74%

Click a blue Job Number in the Most Failed Jobs column to open the details for that job.

JOB621	JOB621-63223a7a			×
Status:	Completed	Start Charge:	74.93%	
Start Time:	9/14/2022, 4:32:58 PM	End Charge:	74%	
Robot:	Sim7			

3-6 Battery Info

This section describes how to access and use the battery information.

3-6-1 Battery Info Graphs

To view the AMR and fleet battery status click **Battery Info** on the Menu. The *Battery Info* opens with the default, *Fleet* line graph with 6 battery parameters.



Click the **Compare All Robots** Check Box to view the graphs for all operating AMRs. The Fleet status shows as the green line graph.



To view the battery status for an individual AMR, click the **Individual Robot** selection. Click any of the Performance Details above the graph to view that battery parameter. Refer to *1-5-4 Battery Info* on page 1-10 for more information.

3-7 Map

The following sections explain how to use maps to view the fleet or AMR operating conditions, using the different map types.

3-7-1 Position Density Map

The *Position Density* map displays the traffic patterns within the operating area of the AMR or fleet. The color intensity increases with the frequency at which an AMR enters and exits a map grid cell. The *Fleet, Position Density Map* is the default view when **Map** is selected. The displayed color is based on the normalized, legend color scale. Click the **Map Selection** Drop-down to open the other available maps. Refer to *3-2-2 Map View Controls* on page 3-4 for specific legend and map selection information.



3-7-2 Localization Map

The *Localization Map* shows the average value of the AMR's localization score within a grid cell for the operating area of the AMR or fleet. The localization score is a number ranging from 0 to 100, where higher values represent better accuracy of the cumulative localization score reported by the AMR. If this value drops below 60 it may be necessary to re-localize the AMR. The localization information is generated and collected from all operating AMRs.

Click the **Map Selection** Drop-down and select **Localization Map** to view that status.



3

3-7-3 Wireless Quality Map

The *Wireless Quality* Map shows the wireless communication strength within each grid cell for the operating area of the AMR fleet. Use the wireless quality information to maintain or optimize the wireless coverage in the fleet operating areas. Wireless Quality data is reported from each AMR with a relative strength number ranging from 0 to 100. A higher value represents a stronger wireless quality. Refer to *3-2-2 Map View Controls* on page 3-4 for information about the display and operating controls. Click the **Map Selection** Drop-down and select **Wireless Quality Map** to view that status.



3-7-4 Floor Map

The *Floor Map* displays the operating area of the AMR or fleet. This includes the boundaries and obstacles. Click the **Map Selection** Drop-down and select **Floor Map** to view and confirm the configuration of all goals, boundaries and obstacles within the area.



Additional Information

Individual Robot and Fleet views of the Floor Map are identical. Refer to 3-2 Common Operations on page 3-3 for information about the display and operating controls.

3-8 Wireless Diagnostics

The Wireless Diagnostics area is used to analyze wireless network performance and functionality. *Wireless Diagnostics* uses BSSIDs. BSSIDs are MAC addresses for the access point hardware. A FLOW iQ *BSSID* is the human readable alias, created from a name and number, that is system created, to identify the MAC address network access point.

Wireless Diagnostics collects data and displays it as *Spot Details* when the point is clicked in the Signal, Ping, BSSIDs, and Roams maps. Spot Details shows the fleet signal level, not an individual AMR, even when the *Individual Robot* is selected.

Spot Details		:
Coordinates:	X: -15250, Y: -47250	20
Base station:	SimNet1[3] (Ch 48)	-20 +4 Networks -40
MAC Address:	72:3a:0e:54:45:03	
Signal Quality:	Excellent, -44dBm	-100
Ping:	~0.26ms	-120
Roams:	-	36 38 40 42 44 46 48 50 52 54 56 58

Values	Description
Coordinates	X and Y coordinates of that map point
Base Station	Wireless access point and channel
MAC Address	Device MAC address alias generated from the SSID and a number, used for system identification
Signal Quality	Quantitative and numeric value (dBm) of signal at that point, when available
Ping	Ping time, if available
Roams	BSSID connection switch, at that access point.

The scan graph on the right side of the Spot Details identifies the connected base station channel in green, if available. This graph shows the closest channels that may overlap or interfere with the connected channel (base station).

3-8-1 Signal

The Signal area provides information about the wireless signal level received by AMRs in the fleet. Click the **Signal** Button to show the AMR travel points on the map, colored to correspond to the Legend color bar on the right side of the map. Use the Calendar to select the day or time interval for the signal analysis. Refer to *3-2-1 Date/Time Settings* on page 3-3 for more information.



Click a colored AMR travel point in the map to view the **Spot Details** at that point. Refer to 3-8 *Wire-less Diagnostics* on page 3-17 for more information.



Additional Information

The signal strength in this map is shown in dBm while the information presented in the Wireless Quality Map is shown as a relative value. Refer to *3-7-3 Wireless Quality Map* on page 3-16 for more information.

3-8-2 Ping

The time for a packet to transmit from the AMR to the Fleet Manager and back to the AMR is the Ping. Click the **Ping** Button to display the locations where AMRs pinged the Fleet Manager. The locations show as colored travel points. The color of each travel point corresponds to the speed legend on the right side of the map.



Click a specific travel point where a ping occurred, to display the Spot Details for the ping. Refer to *3-8 Wireless Diagnostics* on page 3-17 for more information.

3-8-3 BSSID

Click the **BSSIDs** Button to show all the operating access points for the map. Select an access point to display the Spot Details. Refer to *3-8 Wireless Diagnostics* on page 3-17 for more information.

Click the arrow next to the BSSIDs Button to display and filter the available wireless access points. The one or more active filter access points show in the map. When a filter is selected, a small yellow icon also appears in the BSSIDs button.



Double click any shown access point to open a pop-up with the details for that point. Refer to 3-8 *Wire-less Diagnostics* on page 3-17 for more information.

3-8-4 Other

Click the **Other** Button to display all wireless networks and BSSIDs broadcasting in the operating area. Networks that are detected but not connected to the Fleet Manager show with the antenna symbol as gray, <u>ch6</u>.



Click the **Show/Hide** Button to display a list of both connected and unconnected networks. Select a list item to display that access point in the map. Close the side panel by clicking the **Show/Hide** Button.

Home	Robot Status	Job History	Battery Info	Мар	Wireless Diagnostics	API 00	÷
Fleet	Individual Robot	•	🔗 Signal	🙃 Ping	🗢 BSSIDs 🗸 ((+)) Other 🔁 Roams 🗸		
BSSID	MAC ADDRESS	CHANNEL	PING	SIGNAL STRENGTH			
🗢 SimNet1[1]	72:3a:0e:54:43:55	153	Excellent (~0.49ms)	Good (-52dBm)			
🗢 SimNet1[2]	72:3a:0e:54:43:85	64	Excellent (~0.43ms)	Excellent (-44dBm)	Ch 6		-30
🗢 SimNet1[3]	72:3a:0e:54:45:03	48		Excellert (-44dBm)	SimNet1[5] Ch 165		
♥ SimNet1[4]	72:3a:0e:54:44:41	108		Good (-51dBm)	SimNet1[1]		-70
🗢 SimNet1[5]	72:3a:0e:54:44:35	165	Excellent (~0.33ms)	Excellent (-45dBm)			
⇔ SimNet1[1]	72:3a:0e:54:43:55	153	-	Good (-58dBm)	Ch 44		-100
⇔ SimNet1[2]	72:3a:0e:54:43:85	64	-	Good (-\$1dBm)	Ch 11		う
⇔ SimNet1[3]	72:3a:0e:54:45:03	48		Excellent (-50dBm)			+
⇔ SimNet1[4]	72:3a:0e:54:44:41	108		Good (-62dBm)	Ch 6		-

3-8-5 Roams

When an AMR moves through a facility it connects to different access points based on signal strength and channel availability. These connecting events are called *Roams* and display the map locations where AMR connections change from one BSSID to another BSSID. Click the **Roams** Button and all the access points on the map where roaming occurs show in a purple color.



Click any roaming point to view the roam details in a pop-up. Refer to *3-8 Wireless Diagnostics* on page 3-17 for more information.

Click the Roams drop-down arrow to open the filter option. Select the BSSID alias from each column to display the travel points where AMRs changed connection to access points. Click the double arrow

₹

separating the selected Roams options to show the travel points where AMRs are moving

towards an access point. Click the arrow again to show the travel points where AMRs move away from an access point. Click it to be a double arrow, showing all access point movement.

_			
SimNet1[1]	₽	SimNet1[4]	~
All BSSIDs	5	All BSSIDs	
SimNet1[4]		SimNet1[4]	
SimNet1[1]		SimNet1[1]	
SimNet1[5]		SimNet1[5]	
SimNet1[2]		SimNet1[2]	
SimNet1[3]		SimNet1[3]	

Click the circular arrow in the middle of the drop down to return to the default roaming filter. All Roams will show as purple travel points.

((++)) Other	Roams	~	
	All BSSIDs	5	All BSSIDs
	SimNet1[4]		SimNet1[4]
	SimNet1[1]		SimNet1[1]
	SimNet1[5]		SimNet1[5]
	SimNet1[2]		SimNet1[2]
	SimNet1[3]		SimNet1[3]

3-9 API and Download

 Image: Control book (status)
 Today (12/2002)
 Today (12/2002)</t

The following sections show how to use the FLOW iQ API and Download functions.

3-9-1 API Operation

Use the following procedures to view and understand the FLOW iQ API.

Click the **API** Icon () to open the API documentation page. The page contains the supported HTTP methods, endpoint descriptions and usage examples.

OMRON			Fleet Operations Workspace iQ \rightarrow
	The Flow ID API allows clients to get different types of data from their Mobile Robots.		
	servers Filodity: Bases path on Exterption Monoger →)		
	Battery	^	
	GET /api/v1/battery-info	\sim	
	GEI /api/v1/battery-info/all	~	
	GEI /api/v1/battery-info/charging	\sim	
	GET /api/v1/battery-info/live	~	
	GET /api/v1/battery-info/robots	~	
	GEI /api/vl/battery-threshold	\sim	

Click the right-side arrow to learn how use or try an endpoint.

Returns JSON respon	se with the battery information of the selected robot(s) within the date range. These information includes the battery voltage, distance per state of charge, and timestamps.
Parameters	Try it out
Name	Description
<pre>start_date * required string (query)</pre>	The desired start date to get battery information from the selected robot(s)
	2021-07-20
end_date string (query)	The desired end date to get battery information from the selected robot(s) Default value - start, date
	2021-10-21
STC string (query)	The desired robol(s) from which to get battery information (leave blank to select all robot's) Default value : Empty string
	Sim143
start_time string (query)	The desired shift start time to get battery information from the selected robot(s) Default value : 00:00:00
	10.00:00
end_time string (query)	The desired shift end time to get battery information from the selected robot(s) Default value: -23 59 59
	18:00:00
date_format string (query)	Optional custom date format following Datetime Format Codes
	Default value : %Y-%m-%d
	%Y-%m-%d

Click the **Try it out** Button to enable the function and enter the values into the respective boxes in the *Description* column. Then click the **Execute** Button and view the *Responses*.

3

Returns JSON	(response with the list of robol(s) within the date range. If the date range is empty, th	s default date range is since Jan 1, 1970 until now	
Parameters			Cancel
Name	Devenption		
start_date string (goory)	The desired start date to get the list of robot(s)		
end_date string	The desired end date to get the list of robot(s)		
(query)	2022-10-21		
date_format string (genry)	Optional custom date format following Datetime Format Codes		
1000000	%Y-%m-%d		
l.	Executa	Clear	
Responses			
-II 'accept: Haquest UHL https://10.1 Server response Code I	<pre>b.111.34.131/finds/psj/vf/hattery-infs/relats/start_data=2822-09-384eed_data=28 1.25.181/finds/psj/vf/hattery-infs/relats/start_data=2822-09-284eed_data=2823 1.25.181/finds/psj/vf/hattery-infs/relats/start_data=2822-09-284eed_data=2823 2014/</pre>		12
	"Stat2" } Ivepone hesders		Download
-	contast-langth: 206 contast-lype: mplicition/jam dist: hw.2 to 10.21.55:00:1 000 wfrict-temport-secrity: ma-sget3072000; include5d0mmin; preload -crutest-typesprime: neariff -frame-option:: DDV		

Click the **Download** Button to save the json.

Return to the main API page by clicking the **Cancel** Button.

Return to the FLOW iQ Main Page by clicking the Flow Operations Workspace iQ Button.

3-9-2 Download

Use the following procedures to download FLOW iQ graphics.

1 For any view, click the **Download** Icon (**b**) to open the Download panel.

PDF	PNG	JPG				
Include all Graphs						
	Download					

2 Download the Information Area view, using the Download panel, by selecting the format and clicking the **Download** Button.



3 Download the Information Area and the Side Bar graph, using the Download panel, by selecting the format and clicking the **Include all Graphs** Check Box, and click the **Download** Button.



3 Operation

OMRON Corporation Industrial Automation Company

Kyoto, JAPAN

Regional Headquarters

OMRON EUROPE B.V. Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands Tel: (31) 2356-81-300 Fax: (31) 2356-81-388

OMRON ASIA PACIFIC PTE. LTD. 438B Alexandra Road, #08-01/02 Alexandra Technopark, Singapore 119968 Tel: (65) 6835-3011 Fax: (65) 6835-2711
 OMRON ELECTRONICS LLC

 2895 Greenspoint Parkway, Suite 200

 Hoffman Estates, IL 60169 U.S.A.

 Tel: (1) 847-843-7900

 Fax: (1) 847-843-7787

Contact : www.ia.omron.com

OMRON (CHINA) CO., LTD. Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-5037-2220 Fax: (86) 21-5037-2200 Authorized Distributor:

©OMRON Corporation 2023 All Rights Reserved. In the interest of product improvement, specifications are subject to change without notice.